Chapter 5

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The emergence of metacognition: affect and uncertainty in animals

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Introduction: the meaning of 'metacognition'

We assume that readers of this volume will by now have some familiarity with the sorts of para-6 digms that have been used to provide evidence of metacognition in non-human primates. In a 7 common type of experiment (e.g. Smith et al. 2008), animals are trained to perform a primary task such as making a discrimination of some sort between categories (e.g. sparse versus dense) to 9 10 achieve a favoured reward (either immediately, or after a delay; Couchman et al. 2010). After training, the animals are also provided with an 'opt out' response of some kind, which they tend 11 to use in difficult cases where they are more likely to make (or have made) an incorrect judge-12 ment. Opting out generally either avoids the penalty that accompanies a mistaken answer (such 13 as a timeout before there is another opportunity to obtain a reward), or guarantees a less-favoured 14 reward. Such results are said to show that the animals are aware of their own uncertainty, espe-15 cially since similar use of the opt-out response in humans is associated with self-attributions of 16 17 uncertainty.

We fully accept that this body of work, taken as a whole, cannot be explained in low-level asso-18 ciationist terms, as involving mere conditioned responses to stimuli. A great deal of careful 19 experimentation has been done to demonstrate that this is not the case, and we are happy to 20 embrace this conclusion (Beran et al. 2009; Couchman et al. 2010; Smith et al. 2010; Washburn 21 et al. 2010). So it should be agreed that the animals have beliefs about the contingencies of 22 the experiment and take executively-controlled decisions that depend on those beliefs (as well as 23 having goals and other states like emotions, which some have been reluctant to attribute to ani-24 mals; but see Panksepp 2005). 25

However, to say that the animals' behaviour is fully cognitive and executively controlled is not yet to say that it is *meta*cognitive, in the sense in which this term is employed throughout cognitive and developmental psychology. For metacognition is generally defined as 'thinking *about* thinking' (Flavell 1979; Dunlosky and Metcalfe 2009), and therefore as involving metarepresentation. Moreover, metarepresentation in turn is understood to require a representation that represents another representation, or a mental state whose content represents, and is *about*, another mental state.

This definition of 'metacognition' accords with the standard model for classifying and characterizing metacognitive processes in humans (Nelson and Narens 1990; see Fig. 5.1), in which a metalevel monitors, represents, and controls the processes of object-level cognitive systems. Since those who study metacognitive processes in animals often cite this model with approval (e.g. Smith et al. 2003, 2006; Couchman et al. 2010), we assume that is it some version of *this* architecture, or some of its components, that the animals in question are claimed to possess when they are

39 said to have metacognitive capacities. And it should be noted that an important aspect of the

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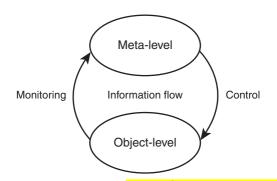


Fig. 5.1 Metacognitive monitoring and control (adapted from Nelson and Narens 1990).

1 Nelson and Narens model has always been that the metalevel contains a metamodel of the object-

2 level, with the metalevel containing metarepresentions of processes and events at the object-level.

3 (See, for example, Nelson and Narens, 1990, p. 126, Principle 2.)

While these definitional issues are important, we should stress that this is only because clarity is important for the progress of science. What ultimately matters, of course, is knowledge of the cognitive structures and processes that underlie the animals' behaviour, not the words we use to express that knowledge. What we will suggest is that some of the behaviour (specifically, so-called 'uncertainty-monitoring' behaviour) that has been claimed to support the presence of a metacognitive architecture can just as well be explained in non-metarepresentational affective terms.

10 Moreover, it should be stressed that even if some of the processes employed by animals in uncertainty-monitoring experiments might appropriately be described in terms of 'monitoring 11 and control', it is another matter to claim that the monitoring in question is metarepresenta-12 tional, or metacognitive in the standard sense. For there are multiple monitoring and control 13 processes in human cognition that are not metarepresentational (Metcalfe 2008). Consider, for 14 example, the use of forward models in the control of action. When motor schemata are activated 15 and sent to the motor system to initiate an action, an efference copy of those instructions is sent 16 to an emulator system that constructs a forward model of the expected sensory consequences of 17 the movement (Wolpert and Kawato 1998; Wolpert and Ghahramani 2000; Jeannerod 2006).¹ 18 This is then received as input by a comparator mechanism that also receives reafferent sensory 19 20 feedback, issuing in swift online adjustments in the action when there is a mismatch. Note that the comparator system is entirely non-metarepresentational in nature: it receives a sensory-coded 21 representation of the intended outcome and compares this with sensory input from the actual 22 outcome as it unfolds. When these fail to correspond, it employs an algorithm that adjusts the 23 motor instructions to bring about a closer match. It doesn't need to represent either the motor 24 intention or the current experiences resulting from the action as such. No metarepresentations 25 are needed, and no one in the field of motor processing thinks that they are employed. 26

This same system is also used offline, when subjects mentally rehearse potential actions for purposes of decision-making. In such cases a motor schema is activated, and although the instructions that would normally be sent to the muscles have been inhibited, the emulator system goes ahead and constructs a representation of the expected sensory consequences. This sensory representation can be 'globally broad-cast' (in the sense of Baars, 1988) when attended to, thus being made available to a range of systems to draw inferences and evaluate the action. We return to these points later in the chapter.

We will assume, then, that those who propose metacognitive explanations for the behaviour of animals in uncertainty-monitoring experiments intend this in the standard sense: they are claiming that the animals metarepresent their own states of uncertainty, and modify their behaviour as a result. We will suggest, in contrast, that the data can equally well be explained in nonmetarepresentational terms. First, however, we propose to situate the issue within a wider debate about the evolutionary emergence of metarepresentational capacities.

7 The phylogeny of metarepresentation

Metacognition and mindreading (or 'theory of mind') are widely believed to overlap (at least) in 8 their psychological bases and evolutionary histories. This is because both rely, fundamentally, on 9 metarepresentation: the representation of mental states. In the case of mindreading, this involves 10 attributing mental states to others, while in metacognition we attribute mental states to ourselves. 11 When one attempts to explain the adaptive advantage that these capacities supplied to our ances-12 tors, a notion of control is invoked in each case. Mindreading allows us to predict the behaviour 13 of others in order to control our own (social) behaviour. Hence, mindreading is thought to have 14 evolved to navigate an increasingly complex social world, engaging with multiple conspecifics in 15 groups with complex social organization. Metacognition, in contrast, allows us to monitor and 16 control object-level systems in our own mind, enabling us to learn and reason more flexibly. 17

Metarepresentation then features in both mindreading and metacognition, but in the service of rather different functions (social cognition versus cognitive control). This leads us to ask which function of metarepresentation is evolutionarily prior (as well as how this bears on the question of human cognitive architecture). The question of prioricity naturally suggests two kinds of account of the evolution of metarepresentational capacities.²

According to one approach, the capacity to represent one's own mental states (or some subset 23 thereof) evolved first (Couchman et al. 2009), presumably to enable animals to accrue the bene-24 fits of metacognitive monitoring and control. Once evolved, the conceptual and inferential 25 resources involved were later exapted for attributing mental states to other agents. There are two 26 main ways in which this could have happened, partly motivated by different views of human 27 mindreading. Either these first-person resources were redeployed to form the basis of a distinct 28 mindreading faculty of the sort defended by Nichols and Stich (2003), or they were combined 29 with emerging capacities for imaginative perspective-taking to enable simulations of the mental 30 31 lives of others (Goldman 2006). We will refer to these as 'first-person-based' accounts of the evolution of metarepresentation, while making no attempt to adjudicate between dual-mechanism 32 and simulationist variants. 33

According to the alternative approach, a capacity to attribute mental states to other agents 34 35 evolved first, driven by the exigencies of social living and resulting in an innately channelled mindreading faculty of some sort. But this mindreading-based account also admits of two main vari-36 ants. According to one, a core *capacity* to make self-attributions would have been present from 37 the start, since there would have been nothing to prevent subjects from turning their mindreading 38 abilities on themselves, treating the self as an agent like any other. A disposition to attribute men-39 tal states to oneself on a regular basis would only have required the motivation to direct one's 40 41 attention accordingly (Carruthers 2011). According to the other variant of a mindreading-based account, in contrast, some sort of self-monitoring mechanism was subsequently added to the 42

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² We assume that no one should now think that these capacities result from general learning, and that everyone should agree that they are innately channelled in development to some significant degree. While these assumptions go undefended here, they are in fact supported by large and varied bodies of data. See Carruthers (2011) for further discussion.

third-person mindreading system, enabling direct (non-sensory) access to one's own mental
states (Frith and Happé (1999) seem to have in mind something like this). In this case we propose *not* to remain neutral between the two variants, but will work with a self-directed-mindreading
account throughout. This provides the cleanest contrast with first-person-based approaches. And
there is, in fact, a good deal of evidence against the monitoring-mechanism alternative (see
Carruthers 2011).

We will shortly compare the first-person-based and mindreading-based accounts of the evolu-7 tion of metarepresentation with respect to the predictions that each makes regarding the com-8 parative data. But first it is worth noting an apparent anomaly for the former. This is that it is 9 widely agreed among psychologists that human metacognitive capacities (or at least those of an 10 uncontroversially metarepresentational sort) are far from impressive. For example, one robust 11 finding in the literature is that people's metacognitive judgements of learning are only moderately 12 correlated, at best, with later recall (Leonesio and Nelson 1990; Dunlosky and Metcalfe 2009), and 13 another is that correlations between metacognitive judgements of text comprehension and tests 14 of understanding are often close to zero (Lin and Zabrucky 1998; Maki and McGuire 2002). 15 Moreover, human metacognitive capacities are fragile and cue-based, are late to develop in child-16 hood, and are heavily dependent upon individual differences in personality and local cultural 17 mores for their effectiveness (Stanovich and West 2000; Koriat et al. 2006, 2008; Stanovich 18 2009). 19

These findings are not what might be expected if metacognitive abilities had a long evolution-20 21 ary history and are innately channelled in development. In contrast, everyone agrees that human mindreading capacities are remarkably good (although admittedly we lack any shared metric for 22 comparing mindreading capacities with metacognitive ones). More importantly, we now have 23 ample evidence of their early emergence in human infancy (Southgate et al. 2007, 2010; Surian 24 et al. 2007; Song et al. 2008; Buttelmann et al. 2009b; Scott and Baillargeon 2009; Scott et al. 2010). 25 This is just as might be predicted by a mindreading-based account of the evolution of metarepre-26 sentational abilities. 27

It could be replied, of course, that biological structures need only deliver small adaptive advan-28 tages in order to be selected for, especially over a long time-frame. And it is possible that metarep-29 resentational capacities evolved initially for first-person metacognitive uses, after which the main 30 adaptive pressure became a social one. This would explain the seemingly poor metacognitive 31 capacities of humans combined with excellent mindreading. One might expect, however, that if 32 metacognitive capacities had been selected for among our ancestors, then they would have come 33 under additional adaptive pressure (leading to further robustness and reliability) when learning 34 and decision-making become increasingly complex through the evolution of the hominin line. In 35 any case the contrast between human native capacities for metacognition, on the one hand, and 36 mindreading, on the other, appears striking, and provides some indirect support for a mindreading-37 based account of the evolution of metarepresentation. 38

39 Predictions for comparative psychology

If metarepresentational capacities evolved initially for metacognitive monitoring and control, 40 then one might expect to find creatures capable of metacognition who are *in* capable of mindread-41 ing (or at least, who are incapable of mindreading of a sort that requires equivalent metarepresen-42 tational resources; see later). At any rate, on this view there must once have been such creatures. 43 Moreover, if creatures of this sort were now discovered, then it would provide significant support 44 for a first-person-based account of the emergence of metarepresentation. For the mindreading-45 based account predicts, in contrast, that metarepresentational capacities should emerge in parallel 46 for self and other (while perhaps allowing that other-directed metarepresentation might precede 47

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1 equivalent forms of metacognition, if, for example, the animals aren't initially motivated to
2 attend to their own mental states). This is because metacognition is held to result from (or at least

3 to employ the conceptual and computational resources of) self-directed mindreading.

The qualification about 'equivalent metarepresentational resources' is important. This is 4 5 because it is widely agreed among developmental psychologists that mindreading admits of two distinct varieties, which emerge at different points in the course of infant development (Wellman 6 1990; Leslie 1994; Baron-Cohen 1995; Gopnik and Meltzoff 1997; Song and Baillargeon 2008). 7 One is a form of goal/perception/knowledge-ignorance psychology that appears during the first 8 year of life. Infants at this stage can represent the goals of other agents, as well as track what 9 aspects of the world those agents do and do not have perceptual access to. As a result, infants at 10 this age form appropriate expectations of agents who act in states of knowledge or ignorance 11 12 respectively. But at this stage (generally referred to as 'Stage 1'), infants are incapable of representing the false belief of another agent, or of forming expectations based on how things appear to the 13 other agent. These latter capacities only emerge toward the end of the fourth year of life (in lan-14 guage-based tasks), or by the middle of the second year of life (when non-verbal measures of 15 competence are employed). Moreover, it is widely believed that the difference between Stage 1 16 17 and Stage 2 mindreading is one of domain-specific conceptual and/or computational competence, rather than resulting merely from performance factors. For it is thought that the capacity to pass 18 Stage 2 tasks depends on an appreciation that mental representations can be *incongruent* with 19 reality (as in a false belief), as opposed to merely *omitting* an aspect of reality (as happens in 20 ignorance).³ 21

There is now evidence of Stage 1 mindreading capacities in non-human animals, not only 22 among other primates such as chimpanzees and rhesus macaques (Hare et al. 2000, 2001, 2006; 23 Flombaum and Santos 2005; Melis et al. 2006; Santos et al. 2006; Buttelmann et al. 2007, 2009a), 24 but also among canids (dogs and wolves; Hare and Tomasello 2005; Hare 2007; Udell et al. 2008), 25 26 and corvids (jays, rooks, crows, and the like; Bugnyar and Heinrich 2005, 2006; Dally et al. 2006, 2009; Bugnyar et al. 2007; Stulp et al. 2009). Note that all of these animals live in complex social 27 groups, suggesting that the pressures of social living might have converged on the evolution of 28 simple forms of mindreading capacity in widely separated species (Emery and Clayton 2004), 29 consistent with a version of the 'Machiavellian intelligence' hypothesis (Byrne and Whiten 1988, 30 1997). 31

Given the presence of Stage 1 mindreading in non-human primates, the finding that they may be capable of monitoring their own desires (Evans and Beran 2007), their own perceptual access (Call and Carpenter 2001; Hampton et al. 2004; Krachun and Call 2009), and their own knowledge and ignorance (Hampton 2001, 2005), fails to adjudicate in our dispute. For these findings are consistent with both self-directed-mindreading and first-person-based accounts.⁴

⁴ In fact we have doubts about the strength of some of this evidence. In particular, success in the memory monitoring experiments conducted by Hampton (2001) does not require attribution of knowledge or ignorance to oneself. It just requires the presence or absence of memory. The animal needs to act in one

³ It may yet turn out that this assumption is mistaken. Rather than reflecting differences in mindreading competence, the differences in performance might turn out to result from the differing executive demands of Stage 1 and Stage 2 tasks (Carruthers, forthcoming). If so, then the failures of non-human primates on Stage 2 tasks might likewise result from problems of executive function. This would mean that the meta-cognitive data are incapable of adjudicating in the dispute between first-person-based and mindreading-based accounts of the evolution of metarepresentation. For there would then be no reason to think that non-human primates are capable of forms of metacognition that outstrip their capacities for mindreading, even if they employ Stage 2 metarepresentational capacities in metacognitive tasks.

In contrast, the current consensus among comparative researchers is that no primate species 1 2 other than humans is capable of 'Stage 2' mindreading, which would include a capacity to attribute false beliefs to other agents. For all tests of such abilities have proved negative, even when 3 conducted in competitive situations, and even when paired with knowledge-ignorance tasks that 4 the animals pass (Hare et al. 2001; O'Connell and Dunbar 2003; Kaminski et al. 2008; Krachun 5 6 et al. 2009). So if other primates can attribute such states to themselves, then this would present an anomaly for a mindreading-based account, while providing corresponding support for a first-7 person-based view. 8

While there is no data of quite this kind in the literature, a substantial body of work on uncertainty monitoring aims to show that members of many primate species are capable of monitoring their own states of certainty and uncertainty, and of choosing adaptively as a result. This might be taken to demonstrate that these animals are capable of Stage 2 metacognition, suggesting that they possess the *concept* of false belief, at least, and can apply it in the first person. For one might think that mastery of the concept of uncertainty requires a capacity to understand that one's beliefs are potentially false. Whether or not this is so will be discussed in the next section.

¹⁶ Uncertainty and feelings of uncertainty

Uncertainty, like certainty, is fundamentally a cognitive state, not an emotional one. To be certain 17 of something is to have a high degree of belief that it is the case. (This might be realized in the 18 19 form of an especially strong signal produced by a classifier mechanism, for example, or an especially strong memory trace.) To be uncertain of something is to have a low degree of belief that it 20 is so (perhaps realized in a weak signal from a classifier mechanism, or a weak memory trace). 21 However, each of these states can also give rise to distinctive emotional feelings of confidence or 22 uncertainty. Moreover, each will have other cognitive and behavioural effects as well, including 23 *fluent* cognitive processing (in the case of certainty) and *disfluency* (in the case of uncertainty).⁵ 24 These further consequences of uncertainty will be used to undergird our alternative (non-25 metarepresentational) explanations of the uncertainty-monitoring data in the next section. 26

If animals self-monitor and metarepresent themselves as uncertain of something, then they 27 must be representing that they have a low degree of belief in it. This will require that they possess 28 Stage 2 metarepresentational resources. For it cannot be sufficient to represent that one is certain 29 of something to represent that one knows it (utilizing one of the concepts from Stage 1), and nor 30 can it be sufficient to represent uncertainty to think that one is ignorant. This is because neither 31 knowledge nor ignorance admit of degrees, and nor do they imply some level of incongruency 32 with the world, as do degrees of belief. (Recall that a capacity to represent that a mental state is 33 incongruous with the world is thought to be the hallmark of Stage 2 metarepresentation.) 34 Moreover, in principle the metarepresentational states involved could be based on self-monitoring 35 that is direct (detecting or introspecting a judgement with a low degree of belief) or indirect 36 (detecting and classifying sensory or behavioural cues of the underlying state of uncertainty). 37 Since no one in the human metacognition literature thinks that monitoring is direct, we propose 38 39 to dismiss this possibility in respect of animals also (Koriat 2000; Dunlosky and Metcalfe 2009). In fact it should be stressed that there is general agreement among researchers that human 40

41 metacognitive judgements are *cue based* (Dunlosky and Metcalfe 2009). Judgements about

way if a memory is present, and to act in another if it is not. But in neither case does it need to entertain a metarepresentation of memory. See Carruthers (2008).

⁵ Cognitive fluency is the ease with which information is processed in the mind, and is signalled by such factors as the speed with which a decision is reached or an item is recognized.

1 whether one has learned something or whether one knows something are grounded in sensorily-

accessible and affective cues, such as the ease with which the item in question is processed or the
feeling of familiarity induced by its presentation. For although Hart (1965) once proposed a sort
of direct-access model in order to explain feelings of knowing, his account has attracted very little
empirical or theoretical support since then (Koriat 2000). We should therefore expect that animals, too, will need to base their judgements on indirect cues—perhaps their own disfluency, or
perhaps their own feelings of uncertainty.

Since humans in uncertainty-monitoring experiments must base their reports of their uncer-8 tainty on sensorily-accessible cues of some sort, it is reasonable to assume that the same, or some-9 thing similar, is true of non-human primates. So it will be important to know how feelings of 10 uncertainty should be characterized, as well as what other similar cues might be in the offing. 11 12 What we can say with confidence is that often the feelings in question are negatively-valenced states accompanied by a degree of arousal that is proportional to what is at stake. Feeling uncer-13 tain can feel bad (to a greater or lesser degree), and it can also be agitating when concerned with 14 important matters.6 15

Feelings of uncertainty are caused by underlying states of uncertainty (that is, low degrees of 16 17 belief). It is a separate question, however, what the negative valence component of the feeling is directed toward. What is it that one feels bad about, when one feels uncertain? What situation or 18 state of affairs is it that seems bad as a result of negative valence, in the way that fear makes the 19 threatening object seem bad and anger makes the causes of damage to oneself or to one's own 20 seem bad? One possibility would implicate metarepresentation in the very feeling of uncertainty 21 itself, utilizing metarepresentational resources. It may be that what strikes one as bad is that one 22 has a low degree of belief. On this account, a judgement to the effect that one has a low degree of 23 belief would be built into (or at least accompany) the feelings in question, providing the intended 24 object or target of those feelings. 25

26 What we propose, however, is that feelings of uncertainty (in both humans and animals) are more plausibly seen as directed at the world (in particular, at the primary options for action that 27 are open to one), rather than at one's own mental states. Consider what happens when people 28 engage in the Iowa Gambling Task, for example (Bechara et al. 1994). Subjects are required to 29 select from four decks of cards with different probabilities of winning or losing. Two of the decks 30 produce steady gains in the long-run (while sometimes issuing in big losses), while two produce 31 32 long-term losses (and yet sometimes issue in big gains). After a while subjects begin to make most of their selections from the 'good' decks, but before they are capable of explicit recognition that 33 those decks are better (let alone capable of articulating *why* they are better). Presumably, as a 34 result of previous learning, the good decks are unconsciously appraised as more likely to issue in 35 gains. As a result, the thought of selecting from those decks is positively valenced, making those 36 37 options seem better. But in addition, some minor degree of arousal is also present, since subjects display an increased galvanic skin response when reaching toward one of the bad decks.⁷ 38

⁶ Note that we are not claiming that there is a unique introspectively-accessible feeling that is distinctive of states of uncertainty. Nor do we think that affective changes are always consciously experienced. All we need to be committed to for present purposes is that there will generally be *some* degree of affective change accompanying states of uncertainty, whether consciously experienced or not, and that these can exert an influence on subsequent behaviour.

⁷ Amiez et al. (2003) used a decision-making task equivalent to the Iowa Gambling Task with macaques, but found that the galvanic skin response occurred *after* the animals had made their selection, seemingly in anticipation of a reward. Quite how galvanic skin responses in uncertainty tasks like these are supposed to support Bechara and colleagues' own 'somatic marker' account of affective decision-making is a

We should stress that in cases of this sort the affective changes can be quite minor, and may pass 1 2 unnoticed by the subject. Yet still the good options seem good and the bad options seem bad, with effects on behaviour that can be quite significant. Certainly in humans, minor forms of affective 3 priming can have large behavioural consequences. For example, Winkielman et al. (2005) used 4 briefly presented, backward-masked, happy and angry faces (which were never consciously per-5 6 ceived) before subjects sampled a novel beverage. Thirsty subjects primed with positive affect drank twice as much of the beverage as those primed with negative affect, and in another condi-7 tion, they offered to pay twice as much for a can of the drink having taken just a sip. Yet these 8 unconscious primes had no discernable effects on the subjects' mood. 9

In fact we think that uncertainty-based decision-making may be best understood as of-a-piece 10 with affectively-based decision-making generally, of the sort characterized by Damasio (1994), 11 Gilbert and Wilson (2007), and many others. On this kind of account one runs the instructions 12 for a motor action offline, using the efference copy to generate a forward model of its outcome (as 13 described in the first section). When attended to, this is globally broadcast as an imagistic repre-14 sentation of the action, which one's evaluative and emotional systems receive and respond to. The 15 result is some degree of positive or negative affect, which provides the motivation to execute the 16 action or to seek an alternative means to the goal (or to pursue an alternative goal). On this kind 17 of account feelings of uncertainty would consist of negatively valenced affect that is caused by the 18 thought of an otherwise-attractive action, and that is directed toward the situation represented in 19 the content of that thought. (It is the performance of the action that seems bad as a result, not the 20 21 fact that one is thinking about it.)

There is some reason to believe that members of other primate species might be capable of such 22 processes of mental rehearsal and affective evaluation, underlying their limited capacity for 23 advance planning (Sanz et al. 2004; Mulcahy and Call 2006), and perhaps also explaining instances 24 of 'insight' behaviour (see Carruthers 2006, for discussion). And indeed, a similar capacity might 25 be more widespread still. Think of the cat that crouches down as if to leap, *literally* rehearsing (the 26 first stages of) a difficult leap from a roof to a nearby tree. Presumably the act of representing the 27 action issues in appraisals of likely success, resulting either in positive affect (felt confidence) 28 directed at the intended leap, or in negative affect (felt uncertainty), leading the cat to seek other 29 solutions. 30

In this section we have distinguished uncertainty from the cognitive and affective consequences 31 of uncertainty, and we have pointed out that animals, like humans, will need to rely on indirect 32 cues of uncertainty, even if they do metarepresent such states. We have also suggested that the 33 valence component of feelings of uncertainty is directed at the primary response options, rather 34 than at one's own mental states. While humans engage in many forms of metacognitive decision-35 making, requiring them to metarepresent their own mental states and processes, basic forms of 36 affectively-based decision-making are not metarepresentational in humans. When we represent 37 and respond affectively to alternative courses of action, no metarepresentations need be involved. 38 As a result, in the following section we will suggest that the uncertainty-monitoring data may be 39 explained without ascribing metarepresentational capacities of any sort to the animals involved.⁸ 40

complicated matter, however (Dunn et al. 2006). So it is far from clear that this result undermines their hypothesis. But in any case our view is not committed to the details of this particular theory of the manner in which affective cues influence decision-making. Indeed, our primary focus is on the valence component of affect, rather than on bodily arousal.

⁸ This will mean that even if the evidence suggesting that non-human primates are capable of Stage 1 forms of mindreading proves to be unsound, it will still be the case that the uncertainty-monitoring data fail to

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Affective explanations of the evidence

2 The present section will discuss three distinct non-metarepresentational explanations of the 3 uncertainty-monitoring data from non-human primates. The first is unsatisfying on its own. But 4 each of the others provides a viable alternative to a metarepresentational account. We will focus 5 especially on a valence-based theory that builds on some of the ideas from the previous section.

6 Degrees of belief

One form of non-metarepresentational explanation is proposed by Carruthers (2008), who 7 appeals to degrees of belief and desire, together with ordinary practical reasoning, to show how 8 the uncertainty-monitoring data can be explained. While this account may not be incorrect, it 9 strikes us as incomplete. This is because it is purely cognitive in nature, and fails to provide for the 10 emotional character of uncertainty.⁹ Since humans in such experiments report not only that they 11 are uncertain (in the sense of having low degrees of belief) but that they feel uncertain (and 12 indeed, since a judgement that one is uncertain must be grounded in indirect cues such as feelings 13 of uncertainty), it seems inadvisable to omit an affective component from the explanation. For 14 the results of uncertainty monitoring experiments with humans can parallel the animal uncer-15 tainty-monitoring data quite closely (Smith et al. 2003, 2008; Smith 2005). Accordingly, two 16 further accounts will be outlined here. Each appeals to the consequences of states of uncertainty, 17 while differing from one another in the factors that are utilized. We should emphasize, however, 18 that these accounts are consistent with one another. Each might apply in different kinds of case, 19 or they might combine together in the same cases. 20

21 Affective consequences as cues

One possibility is that the animals in question have learned to use some aspect of their own feel-22 ings of uncertainty as a cue, but without at any time metarepresenting that they are uncertain (i.e. 23 without categorizing their affective experience as a feeling of uncertainty), or thinking that their 24 judgements or memories are likely to be false. In effect, they may be a following a rule like, 'When 25 in a state of *that* sort [uncertainty], opt out and do something different', which would only 26 require possession of an indexical, non-mental, concept. This can explain why the animals are 27 more likely to press the opt-out key in psychophysically difficult cases, and it can also explain how 28 the animals are able to generalize the use of the opt-out key when presented with it in the context 29 of a newly learned discrimination task (Son and Kornell 2005; Kornell et al. 2007). But neither the 30 31 feeling itself, nor the indexical concept used to identify it, need involve metarepresentation. Rather, just as humans are apt to do (Koriat 2000), the animals might utilize their own disfluency 32 or the bodily feelings associated with uncertainty as cues when confronted with difficult cases. 33 We know from the human case that affective states provide experiential cues for metacognitive 34

deliberation (Koriat 2000; Koriat et al. 2006, 2008). For example, differences in affective states during learning or retrieving information are used as cues that reflect the underlying processing dynamics or processing fluency. In the case of information that is easy to process, greater fluency results, causing positive affect (Winkielman and Cacioppo 2001). The extent to which people show confidence in automatic, intuitive, judgements is heavily dependent on processing fluency. This is true, for example, in low-difficulty recognition tasks, where selection can be based primarily on •

support first-person-based views. For uncertainty-monitoring behaviour arguably fails to involve metarepresentations of any sort (whether Stage 1 *or* Stage 2).

⁹ Emotions might, however, be incorporated into the account as a way of implementing the so-called 'gating mechanism' appealed to.

the feeling of familiarity without serial recall (e.g. Mandler 1980), and also in implicit learning
 tasks (Gordon and Holyoak 1983).¹⁰

Disfluent processing, by contrast, has been suggested to play a role in initiating a transition 3 from more automatic processing to more executively-controlled explicit processing (Alter et al. 4 2007). This role for disfluency has been interpreted as a cue for metacognitive processing, but 5 being sensitive to disfluency need not presuppose any capacity for metarepresentation. For what the experiment by Alter and colleagues shows is that disfluent processing causes changes in atten-7 tion, issuing in different forms of cognitive control. And these changes in attention to the task 8 might drive the selection of different reasoning strategies in the absence of metacognitive process-9 ing. Alternatively, disfluent processing might cause subjects to attend to their own increased 10 arousal, for example, which is taken as a cue to reason differently.¹¹ 11

Note that although this sort of account need not involve metarepresentation, it does rely on self-directed forms of attention. For the animals will attend to, and notice, something about themselves (such as their own bodily feelings) in order to learn the cue-based rule in question. So it can appropriately be described as a form of uncertainty *monitoring*, even if the monitoring norder to learn the cue-based explanation, in contrast, is entirely outward-looking or world-directed in character, while likewise finding a basis in what is known about human decision-making.

19 Directed valence

Suppose that animals, like humans, integrate probabilistic information with intended goal out-20 comes to issue in appraisals of the likelihood of success of the options available to them in a 21 decision-making context. In that case, when an animal has a low degree of belief in something 22 (that the pattern on the screen is dense rather than sparse, or that it has just touched the longest 23 of the lines on the screen, for example), then actions that depend upon the truth of that belief will 24 be appraised as unlikely to succeed.¹² Consequently the animal will experience some degree of 25 anxiety when it contemplates pressing the 'dense' key or the 'gamble' option (albeit quite minor, 26 since the stakes are so low). With negative valence directed at the action in question, it will to that 27 extent seem bad or aversive. In such circumstances the primary response options will be seen in a 28 mixed evaluative light. On the one hand they will seem good, since they hold out the possibility 29 of a significant reward; but on the other hand they will seem bad, since they are appraised as 30 unlikely to succeed. The opt-out response, in contrast, will be seen as an unopposed weak posi-31 tive, since it either advances the animal to a new trial without a time-out or issues in a guaranteed 32 less favoured reward. It is not surprising, then, that the animals should press the opt-out key more 33 often in such circumstances. 34

As we noted earlier, this explanation coheres well with what is known about the decisionmaking processes employed by humans. When humans are confronted with choices they will generally rehearse the actions involved in implementing those choices. These representations, when taken as input by the individual's affective mechanisms, will result in some degree of positive or negative affect directed at the option in question. This makes that option seem either good

¹⁰ Here we presuppose a processing-fluency view of feelings of familiarity, in the manner of Jacoby (1991).

¹¹ Note that neither interoception nor proprioception, of the sort that might underlie awareness of arousal, are metarepresentational forms of awareness (although in a loose sense they can be described as 'intro-spective'). Rather, they issue in awareness of properties of the body.

¹² See Balci et al. (2009) for evidence that mice, too, are capable of making swift and accurate assessments of risk. See also Gallistel et al. (2001) for evidence that rats are excellent at tracking random changes in the probability of reward.

or bad (attractive or aversive), in many cases issuing in a decision (unless the subject opts to
 engage in more explicit reflection of some sort).¹³

Smith (2005) makes much of the fact that humans in uncertainty-monitoring experiments 3 have response profiles that closely parallel those of the animals (see also Smith et al. 2008). Since 4 the humans report that they opt out in conditions of uncertainty because they are aware of being 5 uncertain, this is said to give us reason to attribute similar awareness to the animals. But it does 6 not. For basic forms of decision-making in humans don't employ metarepresentational aware-7 ness, as we have seen. So both humans and animals will experience negatively valenced forms of 8 anxiety directed toward the primary response options, resulting from an appraisal of low likeli-9 hood of success. (The latter in turn is grounded in the low degree of belief that attaches to the 10 categorization or judgement underlying the required discrimination.) This will make those 11 12 options appear bad or mildly aversive. Such perceptions, when strong enough, will leave the optout option as the better-seeming alternative. All of this is entirely non-metarepresentational, as 13 we have noted. But humans, with their highly-developed mindreading capacities, will categorize 14 the state they are in as a feeling of uncertainty, either automatically or when asked to explain their 15 choice. This categorization might play no role, however, in their basic decision-making behaviour 16 17 (unless it is first articulated and treated as a commitment). Indeed, their metacognizing might be largely post hoc. 18

What we suggest, then, is that in humans both uncertainty and its influence on behaviour 19 should be dissociable from metarepresentational awareness of uncertainty. To the best of our 20 knowledge this has not been directly tested. But we predict that subjects who have difficulties with 21 mindreading (including those suffering from autism or schizophrenia) might show capacities to 22 make adaptive use of the opt-out key in uncertainty-responding experiments that are spared in 23 comparison with their capacity to identify themselves as uncertain. For example, in one condition 24 subjects might perform the task without making any explicit metacognitive judgements, whereas 25 26 in another they might be required to make such a judgement before deciding whether or not to opt out. Our prediction is that performance in the former condition should be significantly better 27 than performance in the latter, in these populations. 28

²⁹ Further consequences of the accounts

Notice that both of the affect-based explanations mooted here make significant executive demands 30 on the animals in question. In order for feelings of uncertainty to be used as cues to opt out, they 31 32 have to be attended to. And in order for one to feel anxious at the thought of taking a particular action, that action has to be mentally rehearsed. We should predict, then, that the animals are 33 unlikely to make adaptive use of opt-out behaviour in cases where they are required to execute 34 some concurrent task. Note that this prediction is not made by the degrees-of-belief account 35 alone (independent of any role for epistemic emotions). However, it is also a prediction of the 36 metarepresentational account. So the finding that use of the opt-out response diminishes when 37 animals are required to engage in an ancillary task (Smith 2011), does nothing to support a 38 metarepresentational account of uncertainty monitoring over its affect-based competitors. 39

Moreover, each of the affect-based accounts makes the following empirical prediction. Mood manipulations that are effective in reducing anxiety, or drugs that produce such an outcome, should significantly reduce the extent to which animals opt out in conditions of uncertainty.

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¹³ Note that this account deviates slightly from that provided by Damasio (1994), who places more emphasis on the arousal and other bodily components of affect, rather than on the valence component as we do here. For discussion and defence, see Carruthers (2011). And note, too, that even if arousal *is* involved it can be quite subtle, perhaps depending on what Damasio calls *'as if* affect.'

In contrast, the degrees-of-belief account fails to make any such prediction. For it is purely cogni-1 2 tive in nature. Moreover, any metacognitive account that is cast in purely cognitive terms (merely maintaining that the animals are aware of their uncertainty, for example) will likewise fail to make 3 such a prediction. However, mood manipulations, even if successful, would not necessarily sup-4 port an affect-based account of uncertainty-monitoring behaviour over a metarepresentational 5 6 one. For metacognitive theorists can presumably claim that what is represented is an emotional state of uncertainty, and in that case manipulations that reduce anxiety will have the effect of 7 making it harder to monitor and metarepresent the relevant state. 8

9 None of the tests that have been employed to date are capable of discriminating between 10 metarepresentational and non-metarepresentational explanations of uncertainty-monitoring 11 behaviour. So we are forced to fall back on indirect reasons that might favour one or other kind 12 of explanation, of the sort that have been in play up to now. Some further considerations of this 13 kind will form the topic of the next section.

14 Species differences and individual variation

Smith (2005) and others have argued that differences in uncertainty-monitoring behaviour between species support a metarepresentational account. In this section we challenge this interpretation, while also arguing that individual differences in such behaviour among humans may be problematic for first-person-based accounts to accommodate.

19 Species differences

We agree that differences in uncertainty monitoring behaviour across species favour a metarep-20 resentational account over an associative learning competitor, since the species that fail in these 21 tasks (rats and pigeons) excel at such learning (Smith 2005; Smith et al. 2009). But they don't 22 support a metarepresentational account over either of the affectively-based proposals discussed 23 earlier in the 'Affective explanations of the evidence' section. This is because there may be species 24 differences in the extent to which anxiety is created in foraging situations, or differences in the 25 extent to which members of a given species pay attention to or notice their own bodily feelings, 26 or differences in capacities to engage in mental rehearsal of action. None of these differences is yet 27 confirmed. But until they are ruled out, we have no positive reason to believe that the difference 28 between the species is a metarepresentational one. 29

It might be claimed that differences in uncertainty-monitoring behaviour among distinct spe-30 cies of monkey provide a greater challenge for non-metarepresentational accounts (Beran et al. 31 2009; cf. Basile et al. 2009). Capuchin monkeys, in particular, rarely if ever make use of the opt-32 out response, even after numerous trials, and even under conditions designed to bias the mon-33 keys toward using the opt-out response. Macaque monkeys, in contrast, show response profiles 34 that closely parallel those of humans. It should be obvious from the previous discussion, however, 35 that there are multiple types of resource that could potentially be used to explain these differences 36 without appealing to metarepresentational capacities, and some of these explanations are 37 independently plausible.14 38

¹⁴ We note that Beran et al. (2009) themselves offer accounts of the failure of capuchins in these tasks that don't seem to depend on an absence of metarepresentational capacities. They suggest, for example, that capuchins may lack the ability to appreciate the abstract and indirect benefit of selecting the uncertainty response to maximize reward, leading them to focus on the primary, directly rewarding, options. If this is transposed into a positive account of macaques' success in these tasks, then the account is no longer a metacognitive one. For appreciating an indirect benefit need not require metarepresentation.

It is possible that the two species differ in the extent to which they are apt to experience anxiety 1 2 in foraging situations. In particular, if capuchins feel little or no anxiety when confronted with a difficult discrimination task to gain a food reward, then they will not be motivated to use the opt-3 out key. If macaques are more like humans in this respect, however, then the primary response 4 options will be experienced as aversive in cases of difficult discrimination, making it more likely 5 that the animals will use the opt-out response. Alternatively, capuchins might experience anxiety, 6 but not know what to do with it (i.e. what control operation to adopt). (Compare people who are 7 used to dealing with high degrees of anxiety and those who are not.) These suggestions could be 8 motivated by the following ecological facts. 9

Capuchins are arboreal, living locally in forest environments that provide ample sources of 10 fruits, nuts, leaves, and insects that constitute their primary diet. Although they experience food 11 12 competition within groups, adults are known to share food with unrelated infants, and adults will often share food with one another (De Waal 2000). Macaques, in contrast, are often semi-nomadic 13 with broad ranges, and have colonized a wide set of ecologies, with the largest distribution of any 14 non-human primate genus (Fleagle 1998). Illustrating their flexibility in adapting to new envi-15 ronments, 'weed' macaques (such as the rhesus macaque) have been able to thrive in human 16 17 environments (Richard et al. 1989). Although they, too, are omnivorous, they are subject to intense food competition within groups (Sterck and Steenbeek 1997). It would not be surprising, 18 then, that they might have become adapted to experience and deal with anxiety in difficult forag-19 ing situations, since they face far more uncertainties when foraging than do capuchins. 20

21 Individual differences

22 Smith (2005) also notes that both humans and the other primates in these experiments display 23 similar ranges of individual difference. Some people, and some animals, never make use of 24 the opt-out key, and confine themselves to the primary response options, whereas others opt out 25 adaptively in circumstances where they are likely to make (or to have made) a mistake. It is 26 unclear why this should be thought to support a metarepresentational account, however. (Indeed, 27 we will suggest in a moment that it may cause problems for that account.) In any case, each of the 28 two affect-based theories is capable of explaining this fact.

In the first place, it is well known that there are chronic differences among people in the extent 29 to which they pay attention to the bodily-arousal-component of their emotional states (Barrett 30 1998; Gasper and Clore 2000; Barrett et al. 2004), and one might expect the same to be true of 31 32 other primates. Such individuals are unlikely to notice the manifestations of their own state of uncertainty, and so will be less likely to learn to use them as cues to opt out. It is also well known 33 that there are chronic differences between people (and presumably other primates) in the extent 34 to which they become anxious in everyday situations. Those who aren't easily made anxious will 35 fail to see the primary response options as bad or aversive, and so will lack any motivation to use 36 the opt-out response, whereas those who are more easily made anxious will opt out more often. 37 38 In contrast, while all views might predict that there will be individual differences in the *extent*

to which people make use of the opt-out option, the fact that some people (and animals) almost 39 never employ it is harder for a metacognitive theorist to accommodate. How hard it is will be a 40 function of the proportion of subjects who never opt out. If such people are rare, then they might 41 42 be considered the tail-ends of a normal distribution. But if they are numerous, and the normal distribution curve is not very steep, then this will be more problematic. For recall that the concep-43 tual and inferential resources necessary to monitor one's own mental states are claimed to have 44 been selected for precisely because of the adaptive advantages that they yield in situations like this. 45 It would therefore be puzzling if there should turn out to be many individuals who nevertheless 46

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fail to make use of those resources. (It would much as if we found a significant proportion of 1 people who never make use of episodic memory.) For there is surely just as much need for people 2 to monitor uncertainty as there ever was in our evolutionary past. If metarepresentional resources 3 evolved, in part, to enable animals to monitor their own uncertainty and respond adaptively, then 4 one would expect that those resources would be regularly and reliably employed by the vast 5 majority of normal individuals. The affect-based accounts, in contrast, can appeal to widespread individual differences that are already known to exist. 7 It seems, then, that in the absence of a direct experimental test, there are no indirect reasons to 8

favour a metarepresentational account of the uncertainty-monitoring data over its affect-based 9 competitors; indeed, there are some reasons to prefer the latter.¹⁵ 10

Conclusion 11

We conclude that existing uncertainty-monitoring experiments with non-human primates fail to 12 discriminate between a metacognitive (metarepresentational) account and those that rely on 13 non-metarepresentational uses of feelings of uncertainty. Until experiments that might tease 14 apart these differing explanations have been done, a metarepresentational account of the uncer-15 tainty-monitoring data is unsupported. As a result, while we have good reason to think that these 16 animals are capable of taking executively controlled decisions in many ways like our own, we 17 presently have no reason to prefer a first-person-based account of the evolutionary emergence of 18

metacognition over its mindreading-based competitor. 19

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¹⁵ There is one final possibility that has not been discussed here. This is that epistemic emotions like uncertainty are non-conceptual forms of first-person metarepresentation in virtue of their function of informing us of the underlying risk of epistemic failure. See Proust (2009a, 2009b) for defence of a view of this sort. (Note, however, that Proust herself declines to use the language of 'metarepresentation' in this connection.) For a critique of this idea see Carruthers (2011).

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